



# GARPUR Final Conference

Development of new reliability criteria.



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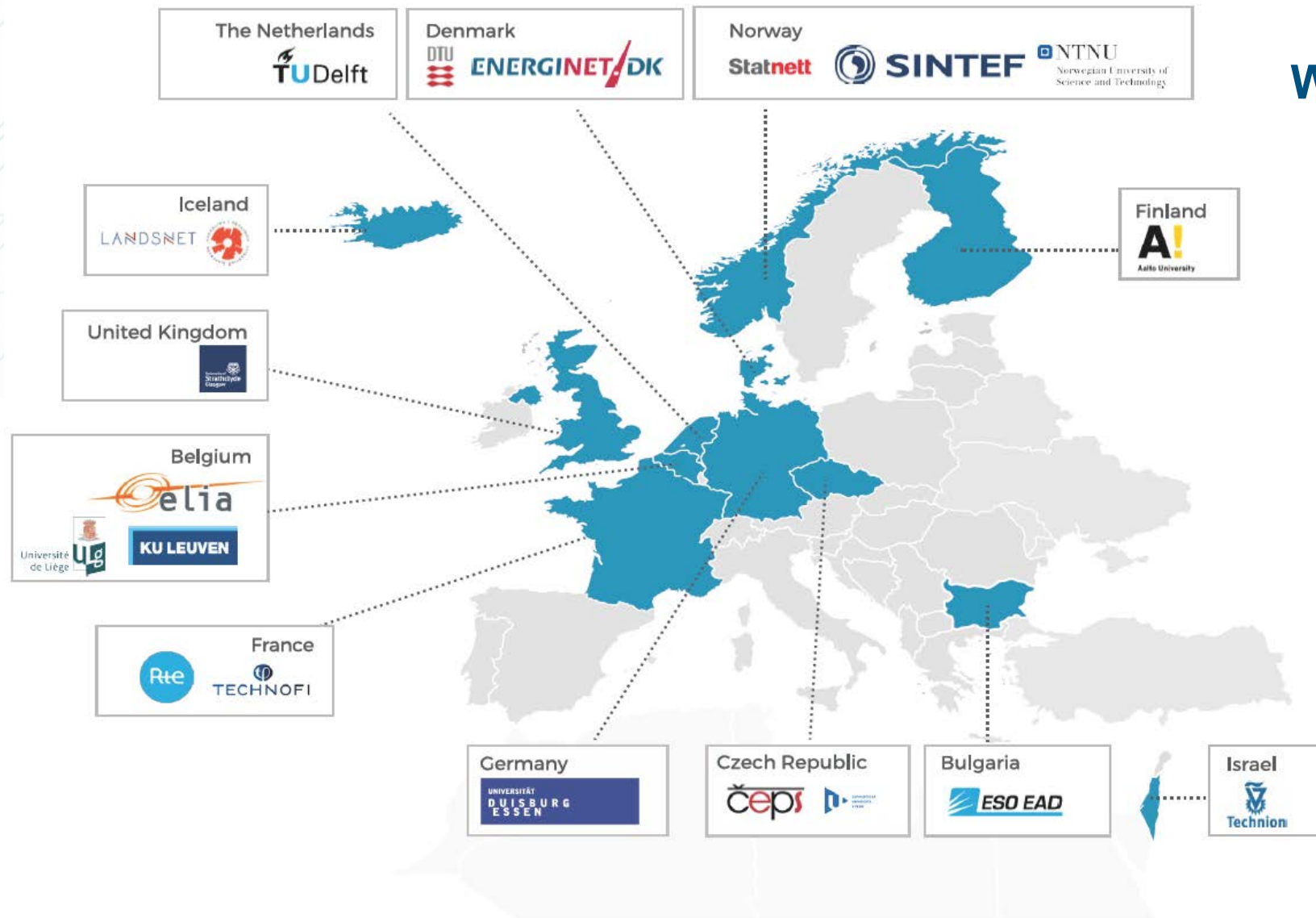
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**1 public deliverable**  
**1 restricted deliverable**  
**3 internal deliverables**



# Outline of Presentation



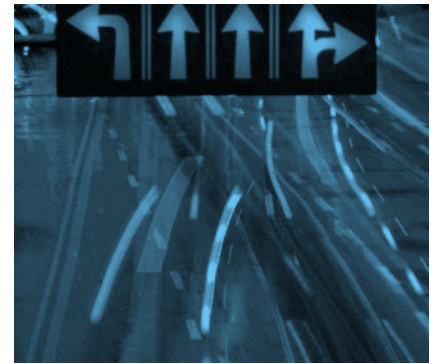
**Revisiting reliability management**



**The GARPUR Reliability Management Approach & Criterion (RMAC)**



**Proof-of-concept applications & algorithmic implementation**

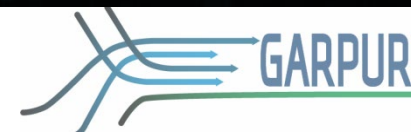


**Conclusions**





# Revisiting reliability management



# Reliability Management



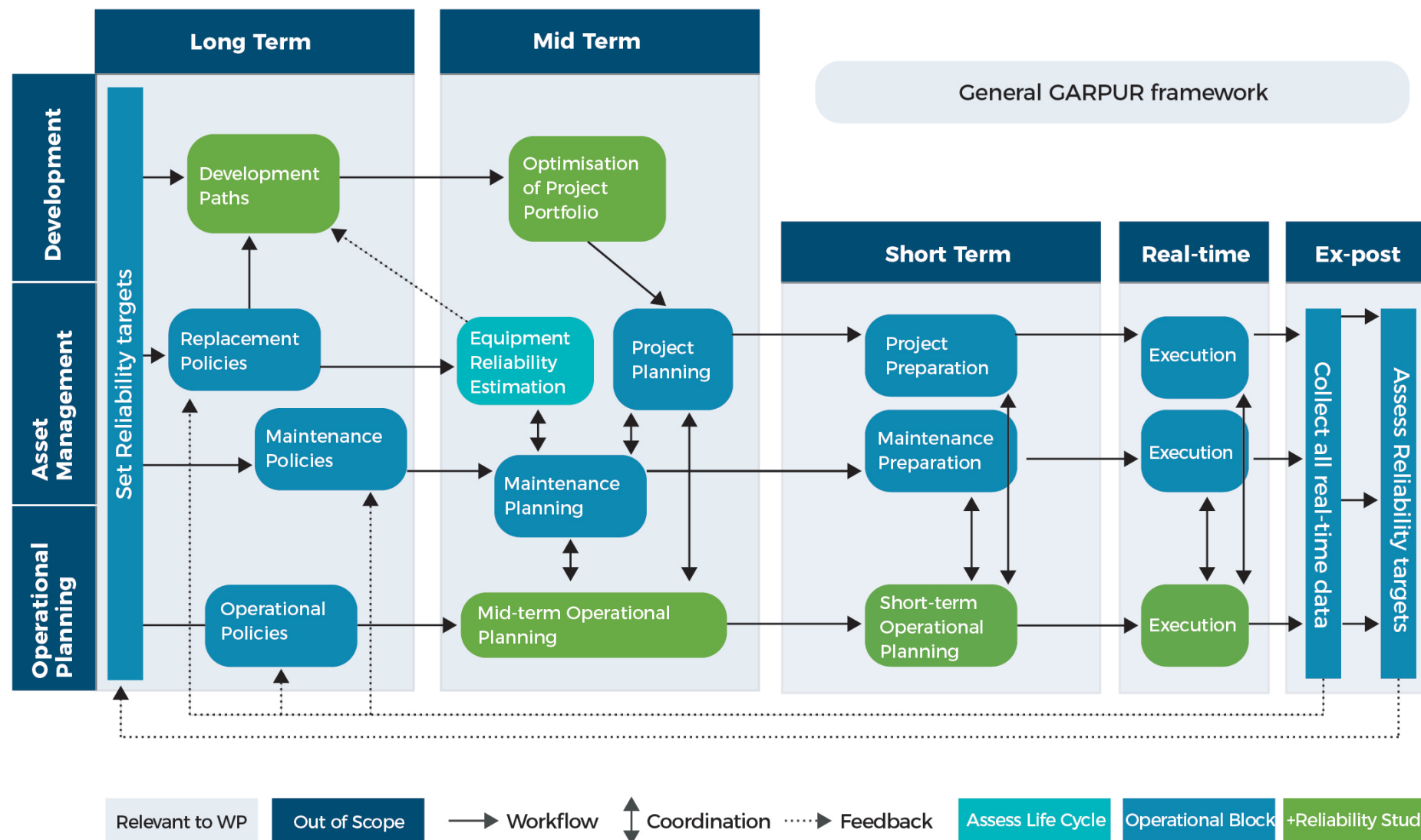
*“Means taking a sequence of **decisions under uncertainty**. It aims at meeting a **reliability criterion** while minimizing the **socio-economic costs of doing so**”*

*“A **reliability criterion** is a principle imposing **the basis** to determine **whether or not the reliability of a system is acceptable**”*



# Reliability Management

- Many different practical problems facing several uncertainties



# Present use of the N-1 criterion (e.g. in Real-Time operation)

## a. Covered next contingencies:

- all single outages (+ possibly some common mode outages).
- 

## b. Acceptable contingency response:

- simulated response within steady-state (and stability) limits.
- 

## c. Economic objective:

- operational costs, combining TSO costs and congestion costs.

# In today's evolving power system

- **N-1** should still work quite well under “average” conditions.
- 
- “Average” conditions **tend to disappear...**
    - **N-1 is over-conservative**, while limiting the integration of **cheap renewables?**
    - **N-1 is under-conservative**, while facing **adverse weather** phenomena, etc?
    - **N-1 is risk-averse**, while avoiding even very **minor & tolerable consequences?**
    - **N-1 is risk-taking**, while neglecting the possible **failure of corrective controls?**

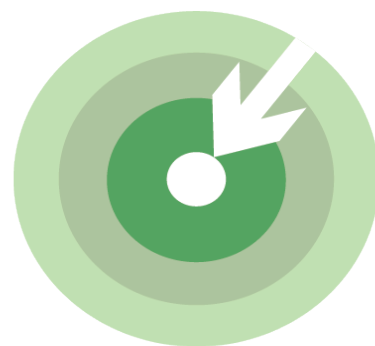


# How to move forward?

- Maintain the **solid “first principles”** from the N-1 approach.

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- Dynamically adapt to more information on ...
  - the spatio-temporal variability **in threat probabilities**;
  - the **socio-economic impact** of service interruptions;
  - **corrective control options** & their possible failure.







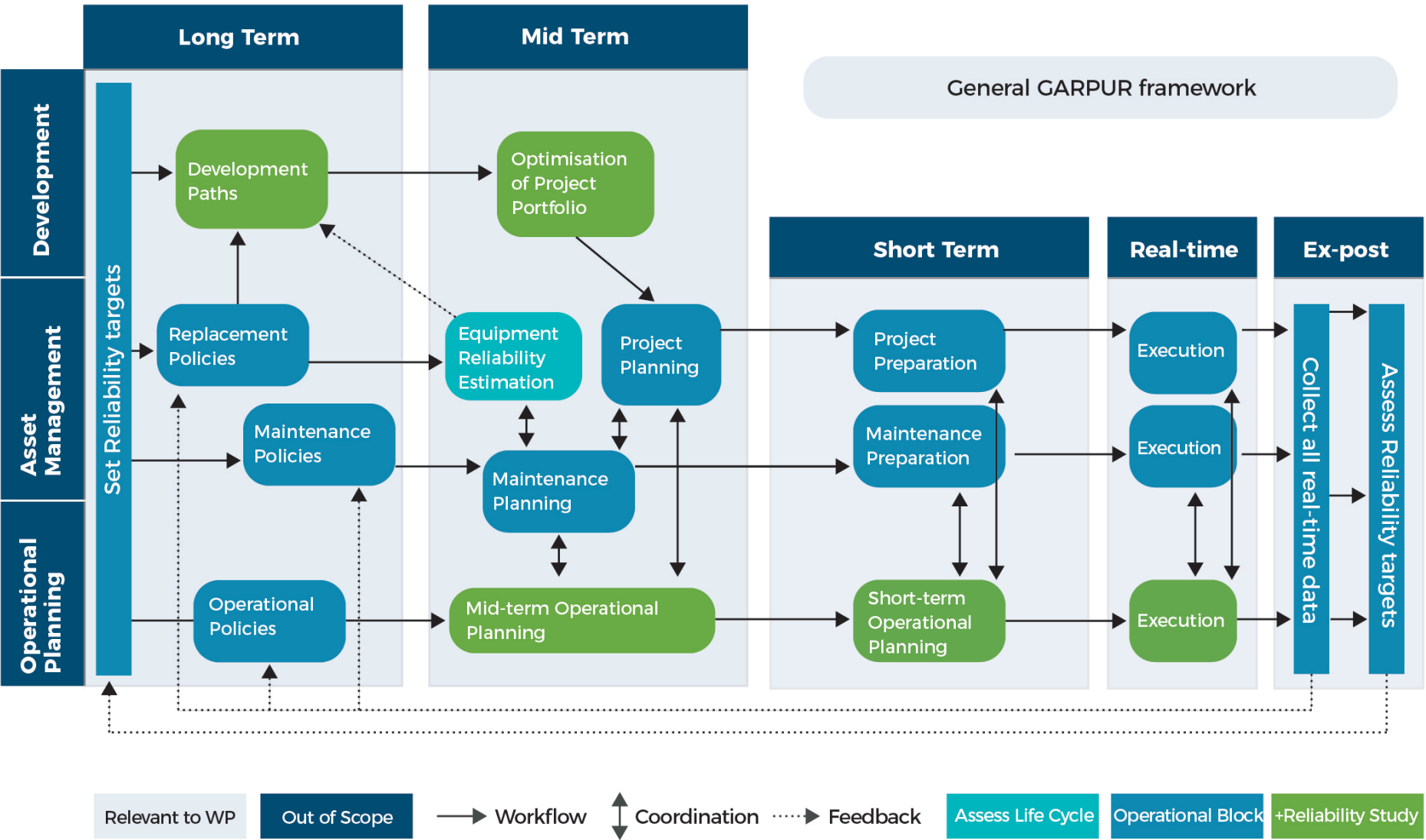
# The GARPUR Reliability Management Approach & Criterion (RMAC)





# Reliability Management

- Many differences practical multi-stage decisions involving uncertainty





# A common model for reliability management

- **Look-ahead horizon:** the period over which decision making is effective ( $t \in [1, T]$ ).
  - **Uncertainties:** modelled as exogenous processes & sequentially resolved ( $\xi_{\{1, \dots, T\}} \in \mathcal{S}$ ).
- 
- **TSO decisions:**
    - firm in the 1<sup>st</sup> stage ( $u_0$ );
    - recourse is adaptive to uncertainty realizations ( $u_{\{1, \dots, T-1\}}$ ).
- 
- **State transition function:** describing relationship between successive states, decisions & uncertainty realizations  $x_{t+1} = f(x_t, u_t, \xi_{t+1})$ .

# For example ...

- **Real-time operation (0'-30'):**
  - First-stage decision: preventive (pre-contingency) control.
  - Uncertainty: contingency occurrence & post-contingency control behavior.
  - Recourse decisions: corrective (post-contingency) control.

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- **Day-ahead operation planning (12h-36h):**
  - First-stage decision: reserve provision, must-runs...
  - Uncertainty: wind/solar power injections, load demand, weather, etc..
  - Recourse decisions: real-time operation over the next day.

---

- **Asset management/System development ...**

# The GARPUR RMAC components



Reliability target



Socio-economic objective



Discarding principle



Relaxation principle



Temporal coherence proxies



# The Reliability target (1/2)

- Modeling the notion of **acceptable system performance** as a (context-specific) set of constraints  $X_\alpha$ ,
- ✓ **trajectory** (i.e., state evolution) acceptable if  $(x_1, \dots, x_T) \in X_\alpha$



- e.g., in **real-time** operation: no **uncontrolled cascades** (loss of stability & too large/long/widespread) **service interruptions**;
- e.g., in **day-ahead** planning: no **infeasible real-time operation**.

## The Reliability target (2/2)

- Adopting a **tolerance level** ( $\varepsilon$ ) on the probability of realizing unacceptable system performance,

$$\mathbb{P}\{(\mathbf{x}_1, \dots, \mathbf{x}_T) \in \mathbf{X}_a \mid \xi_{\{1, \dots, T\}} \in \mathcal{S}\} \geq 1 - \varepsilon$$



- e.g., in **real-time** operation **ensures the probability of avoiding uncontrolled cascades** (loss of stability & too large/long service interruptions);
- e.g., in **day-ahead** planning **ensures the probability of avoiding infeasible real-time** operation.

# The Socio-economic objective (1/2)

- A compound cost function to be **minimized**, blending:
  - the **firm costs** associated to 1<sup>st</sup> stage decisions ( $C_0(x_0, u_0)$ );
  - the **expected cost of recourse** decisions ( $C_t(x_t, u_t)$ );
  - a terminal cost, monetizing the impact of **service interruptions** ( $C_T(x_T)$ ).



- e.g., in **real-time** operation, costs of **preventive** actions (1<sup>st</sup> stage) and **expected** costs of post-contingency **corrective** (recourse), along with service interruption **criticality**;
- e.g., in **day-ahead** planning, costs of **day-ahead decisions** (1<sup>st</sup> stage) and **expected** costs of **real-time** (preventive/corrective+criticality) operation (recourse).



# The Socio-economic objective (2/2)

- A compound cost function to be minimized,

$$C_0(x_0, u_0) + \mathbb{E}_{\xi_{1, \dots, T} \in \mathcal{S}} \left\{ \sum_{t=1}^{T-1} C_t(x_t, u_t) + C_T(x_T) \right\}$$

**Aggregate Risk**



- e.g., in **real-time** operation, risk equals **expected corrective control costs & service interruption costs** induced by **contingencies, corrective control failures**;
- e.g., in **day-ahead** planning, risk equals **expected real-time costs** (pre- and post- contingency controls, service interruption) induced by uncertainties on **wind power injection/load forecast errors, etc..**

# The Discarding principle (1/2)

- In practice the uncertainty space is **XXXL**,
- we propose to **only neglect** those uncertainty realizations whose joint **risk falls below a discarding threshold ( $\Delta E$ )**, expressed in euros.



- e.g., in real-time operation, dynamically **adapt the contingency list** vs the **probability x service interruption impact** of credible contingencies.
- e.g., in day-ahead planning, **select & prepare for scenarios** (for instance, wind forecast errors) as per **probability x real-time cost** of operation.

# The Discarding principle (2/2)

- Discard uncertainty realizations  $S \setminus S_c$ :

$$\mathbb{E}_{\xi_{1,\dots,T} \notin S_c} \left\{ \sum_{t=1}^{T-1} C_t(x_t, u_t) + C_T(x_T) \right\} \leq \Delta E$$



- e.g., in real-time operation, dynamically adapt the contingency list vs the **probability x service interruption impact** of credible contingencies.
- e.g., in day-ahead planning, select & prepare for scenarios (for instance, wind forecast errors) as per **probability x real-time cost** of operation.



## RMAC Socio- economic objective



$$C_0(x_0, u_0) + \mathbb{E}_{\xi_{1, \dots, T} \in S_c} \left\{ \sum_{t=1}^{T-1} C_t(x_t, u_t) + C_T(x_T) \right\}$$

cost functions ( $C_{\{0, t, T\}}$ )  
+ state transitions  $x_{t+1} = f(x_t, u_t, \xi_{t+1})$

## RMAC Reliability target



$$\mathbb{P}\{(x_1, \dots, x_T) \in X_a | \xi_{\{1, \dots, T\}} \in S_c\} \geq 1 - \varepsilon$$

acceptability constraints ( $X_a$ )  
+ tolerance level ( $\varepsilon$ )

## RMAC Discarding principle

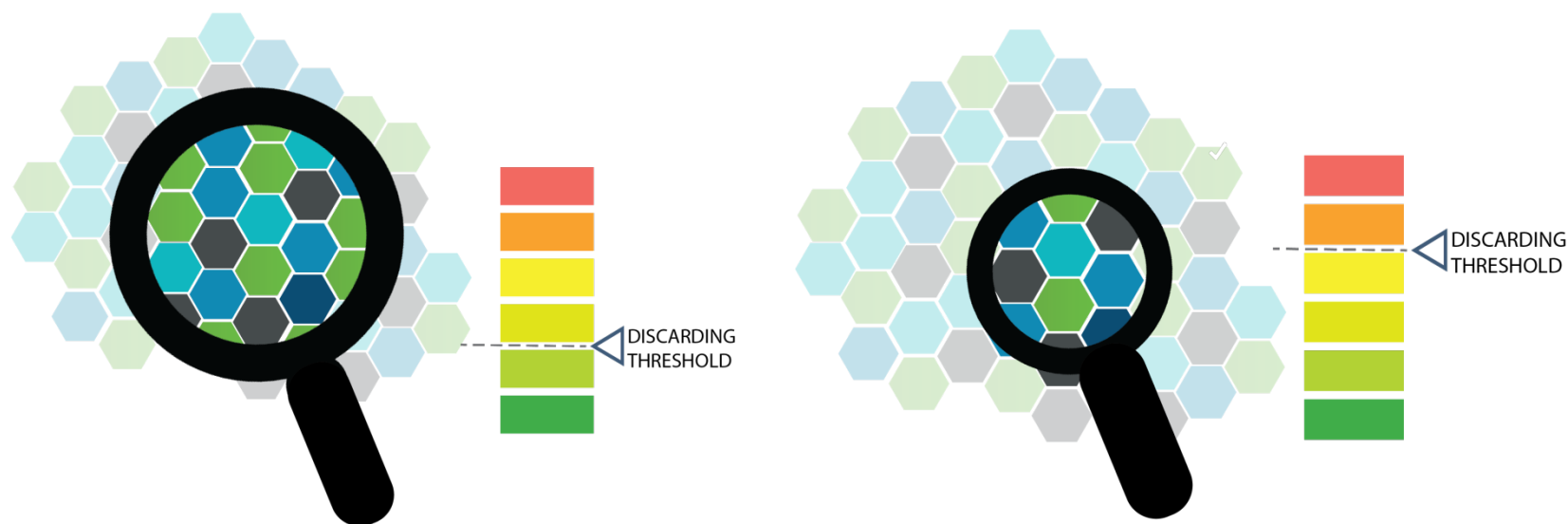


$$\mathbb{E}_{\xi_{1, \dots, T} \notin S_c} \left\{ \sum_{t=1}^{T-1} C_t(x_t, u_t) + C_T(x_T) \right\} \leq \Delta E$$

discarding threshold ( $\Delta E$ )

# Relaxation principle

- In practice, it remains possible to arrive at a situation when **no available decision** leads to complying with both the reliability target & discarding principle!
- We propose, in any such case, to **progressively increase (relax) the discarding threshold** parameter, until the reliability target can be met;
- in other words to accept **as less additional risk** as necessary.



# Temporal coherence proxies



- What's a proxy?
  - A **simplified model** of a decision making context (e.g., real-time operation);

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- Where would it be used?
  - in the **socio-economic objective** of an outer context (e.g., day-ahead operational planning) to evaluate a recourse cost component (e.g., real-time operation);
  - in the **acceptability constraints** of an outer context, seeking the feasibility of the inner decision making policy.



# The GARPUR RMAC



- **A unified approach** across all time horizons & decision making contexts.

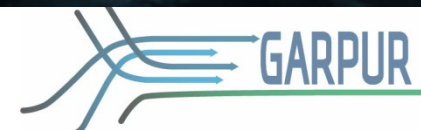
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- **Fundamental components** developed in the common model of reliability management as a **multi-stage stochastic programming problem**;
- and **declined to any problem instance**, from long-term & system development, through mid-term & asset management to short-term planning & operation.





# Proof-of-concept applications & algorithmic implementation





# Overview

- Development of **prototype assessment & optimization algorithms** as per the principles of the GARPUR RMAC.
- Investigation of algorithmic **feasibility, scalability** vs academic benchmarks etc..
- **Demonstrative findings** on the outcomes of the RMAC with respect to the “classical” N-1 assessment & decision making approach.
- Major achievements published in **8 conference papers** (+ a pending journal publication).

```
353
354 for idx in 1:size(Clog1s,1)
355     print(contfile,round(Clog1s[idx,:],0),"\n")
356 end
357
358 for s in 2:Sset
359
360     PdRt[:,1,s]=Pdem[:]+dPD[:,s].*Pdem[: ]
361     PdRt[:,2,s]=voll
362     PwRt[:,s]=WP[:,s]
363     if size(LinAv1S,2) <= CardMax
364
365         LinAvScen[:,1:size(LinAv1S,2),s]=LinAv1S
366         CmatScen[1:size(LinAv1S,2),:,s]=Cmat1S
367
368     else
```

<p>Distributed Scenario-Based Optimization for Asset Management in a Hierarchical Decision Making Environment</p> <p>Gal Dalal, Elad Gilboa, Shie Mannor Department of Electrical Engineering Technion Haifa, Israel gald@tx.technion.ac.il, egilboa@tx.technion.ac.il, shie@ee.technion.ac.il</p> <p>Abstract—Asset management attempts to keep the power system in working conditions. It requires decisions between multiple entities and long term advance. In this work we introduce a formulation as a stochastic optimal control problem with three hierarchical layers of decision terms, short-term and real-time. We approximate techniques for efficient implications a maintenance schedule</p>	<p>ing In Electricity Grid Management</p> <p>GALD@TX.TECHNION.AC.II EGILBOA@TX.TECHNION.AC.II SHIE@EE.TECHNION.AC.II</p>
<p>Probabilistic Reliability Management Approach and Criteria for Power System Real-time Operation</p> <p>Efthymios Karangelos and Louis Wehenkel Department of EE&amp;CS, Institut Montefiore, University of Liège, Belgium {e.karangelos, lwehenkel}@ulg.ac.be</p> <p>Abstract—This paper develops a probabilistic approach for power system reliability management in real-time operation where risk is a product of (i) the potential occurrence of contingencies, (ii) the possible failure of corrective (i.e., post-contingency) control and, (iii) the socio-economic impact of service interruptions to end-users. Stressing the spatiotemporal variability of these factors, we argue for reliability criteria assuring a high enough probability of avoiding service interruptions of severe socio-economic impact by dynamically identifying events of non-negligible implied risk. We formalize the corresponding decision making problem as a chance-constrained two-stage stochastic programming problem, and study its main features on the single</p>	<p>control are highly complicated and systems such as the power grid arise because of such as generation must meet and transmission lines can not al capacity. Further complications of decision making in dif-</p> <p>contingencies (such as the N-1 or N-k approaches). Indeed, in the presence of spatiotemporal variability, these can not consistently maintain the system reliability level nor optimize its socio-economic impact on system end-users [7], [8].</p> <p>A. Proposal Motivated by these facts, we propose a probabilistic Reliability Management Approach and Criterion (RMAC) as a synthesis of the three following basic ingredients: 1) A reliability target: it ensures that the probability of</p>

# Summary of applications

- **Real-time operation (Rt-RMAC):**
  - risk assessment & security constrained optimal power flow (SCOPF).

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- **Short-term operational planning (St-RMAC):**
  - risk assessment & security constrained optimal power flow (SCOPF);
  - machine learning of proxies for reliability management.

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- **Mid-term & asset management (Mt-RMAC):**
  - simulation based stochastic optimization for outage scheduling.



# Real-time RMAC (Rt-RMAC) prototypes

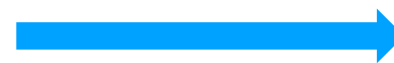
- vs uncertainty on **contingencies & corrective control failures**

## Discarding problem



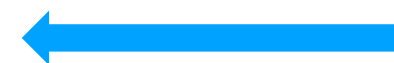
How to select a manageable contingency subset as per the **RMAC discarding principle?**

Contingency



Subset

Optimal



Decisions

## Control problem



Choose **preventive** and/or **corrective control** as per the **RMAC reliability target & socioeconomic objective.**

# Rt-RMAC: algorithmic implementations

- **Discarding problem:**
  - upgraded cascade simulation algorithms originally proposed in the literature to estimate **per contingency interruption costs**;

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- **Control problem:**
  - Security Constrained Optimal Power flow (SCOPF) formulations:
    - a. DC-approximation, **mixed integer linear** problem (MILP);
    - b. full AC- model, **mixed integer non-linear** problem (MINLP).
  - Upgraded **iterative contingency clustering** scheme to focus on MINLP reliability target achievability.

# Rt-SCOPF exemplary result



- **Reliability target functionality**

<i>Tolerance level (<math>\epsilon</math>)</i>	0	$10^{-6}$	$10^{-5}$	$10^{-4}$
<i>Preventively Secured Contingencies</i>	42	41	40	36
<i>Correctively Secured Contingencies</i>	0	1	1	4
<i>Not Secured Contingencies</i>	0	0	1	2
<i>Total</i>	42	42	42	42

- **( $\epsilon=0$ ):** blocks corrective control due to its possible failure,
- **( $\epsilon \gg$ ):** fewer low probability contingencies “covered by preventive/corrective controls.

# Rt Security Constrained OPF

- Deterministic State-of-the-art

$$\min_{\mathbf{u}} CP(x_0, u_0)$$

**preventive**

$$g_0(x_0, u_0) = 0$$

$$h_0(x_0, u_0) \leq \mathcal{L}$$

**intermediate  
post-contingency**

$$g_c^s(x_c, u_0) = 0 \quad \forall c \in \mathcal{C}_c$$

$$h_c^s(x_c, u_0) \leq \mathcal{L}^s \quad \forall c \in \mathcal{C}_c$$

**corrective  
post-contingency**

$$g_c(x_c^{b1}, u_c) = 0 \quad \forall c \in \mathcal{C}_c$$

$$h_c(x_c^{b1}, u_c) \leq \mathcal{L} \quad \forall c \in \mathcal{C}_c$$

$$|u_0 - u_c| \leq \Delta u_c \quad \forall c \in \mathcal{C}_c$$

- GARPUR RMAC approximation

$$\min_{\mathbf{u}, \mathbf{z}, \mathbf{y}} \left\{ C_0(x_0, u_0) + \sum_{c \in \mathcal{C}_c} \pi_c \cdot CC(x_c, u_c) + \sum_{c \in \mathcal{C}_c} \pi_c \cdot \pi_x(c) \cdot CR^{\max} \right\}$$

$$\sum_{c \in \mathcal{C}_c} \pi_c \cdot \pi_x(c) \leq \epsilon_{RT}$$

**reliability target**

$$g_0(x_0, u_0) = 0$$

$$h_0(x_0, u_0) \leq \mathcal{L}$$

$$g_c^s(x_c, u_0, z_c) = 0 \quad \forall c \in \mathcal{C}_c$$

$$h_c^s(x_c, u_0, z_c) \leq \mathcal{L}^s \quad \forall c \in \mathcal{C}_c$$

$$g_c(x_c^{b1}, u_c, z_c) = 0 \quad \forall c \in \mathcal{C}_c$$

$$h_c(x_c^{b1}, u_c, z_c) \leq \mathcal{L} \quad \forall c \in \mathcal{C}_c$$

$$|u_0 - u_c| \leq y_c \cdot \Delta u_c \quad \forall c \in \mathcal{C}_c$$

**continuous &  
discrete auxiliary  
variables**

$$\pi_x(c) = z_c + (1 - z_c) \cdot \sum_{j \in \mathcal{J}} y_{c,j} \cdot \pi_{bf,j} \quad \forall c \in \mathcal{C}_c$$

$$z_c \in \{0; 1\} \quad \forall c \in \mathcal{C}_c$$

$$y_{c,j} \in \{0; 1\} \quad \forall c, j \in \mathcal{C}_c \times \mathcal{J}.$$

**Proper model of most post-contingency controls is anyhow discrete!**



# Short-term RMAC (St-RMAC) prototype

- vs uncertainty on **weather state & renewable power injections**

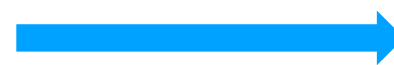
## Discarding problem



How to select a manageable **scenario subset** as per the **RMAC discarding principle**?

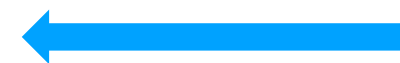


Scenario



Subset

Optimal



Decisions

## Control problem



Choose **planning decisions** as per the **RMAC reliability target & socioeconomic objective**.



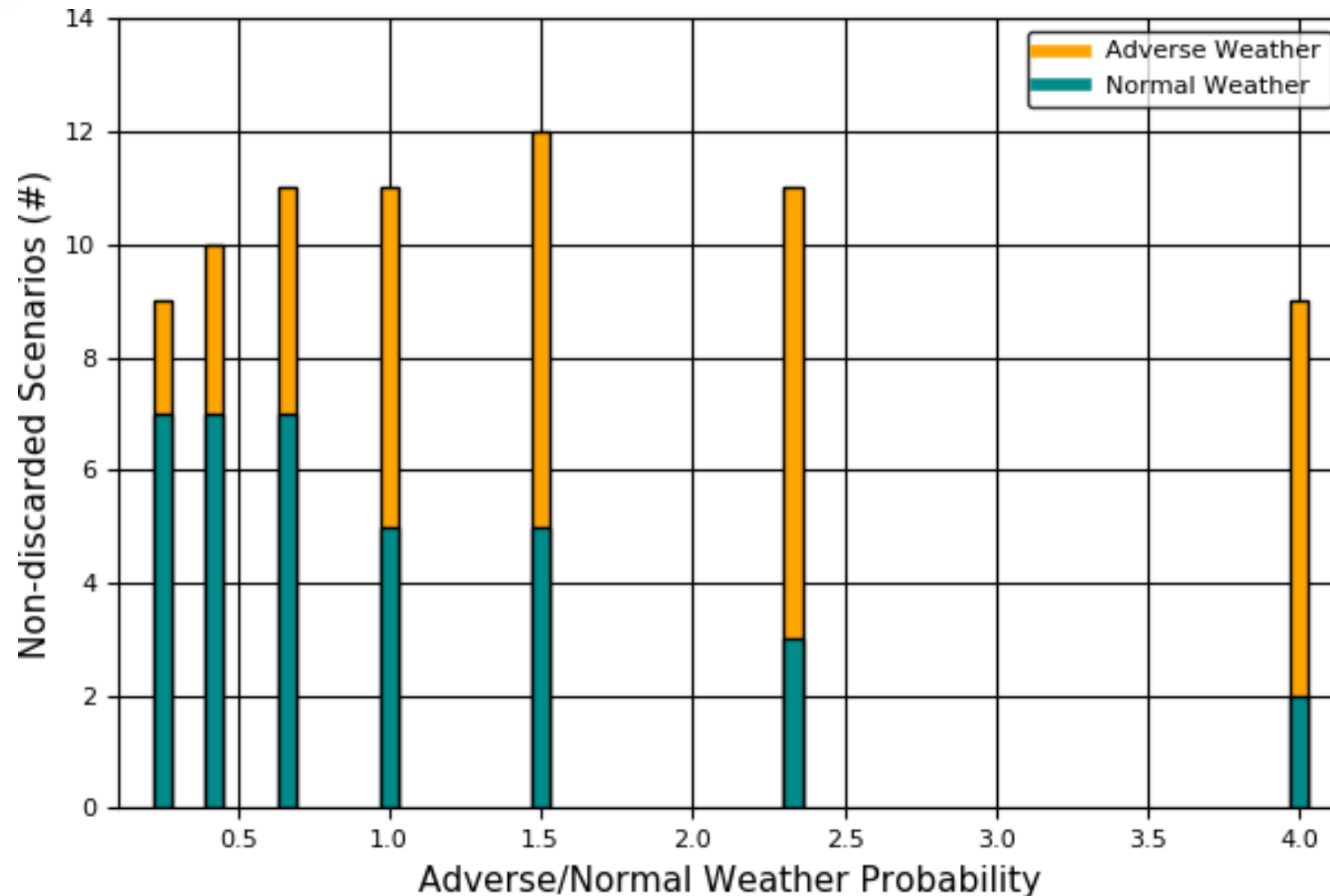
# St-RMAC: algorithmic implementation

- Integrating DC-SCOPF “proxies” of the Rt-RMAC
- 
- **Discarding problem:**
    - per scenario, evaluate the cost necessary to meet the Rt-RMAC;
    - or, if need be, to meet the relaxed version of the Rt-RMAC.
- 
- **Control problem:**
    - 4-stage security Constrained Optimal Power flow (SCOPF) formulated as a mixed-integer programming problem;
    - planning decisions: generation start-up/shut-down & reserve booking.

# St-RMAC exemplary result



- Discarding principle functionality



- Choice of non-discarded scenarios follows the progressive increase in the probability of realizing the adverse weather state.



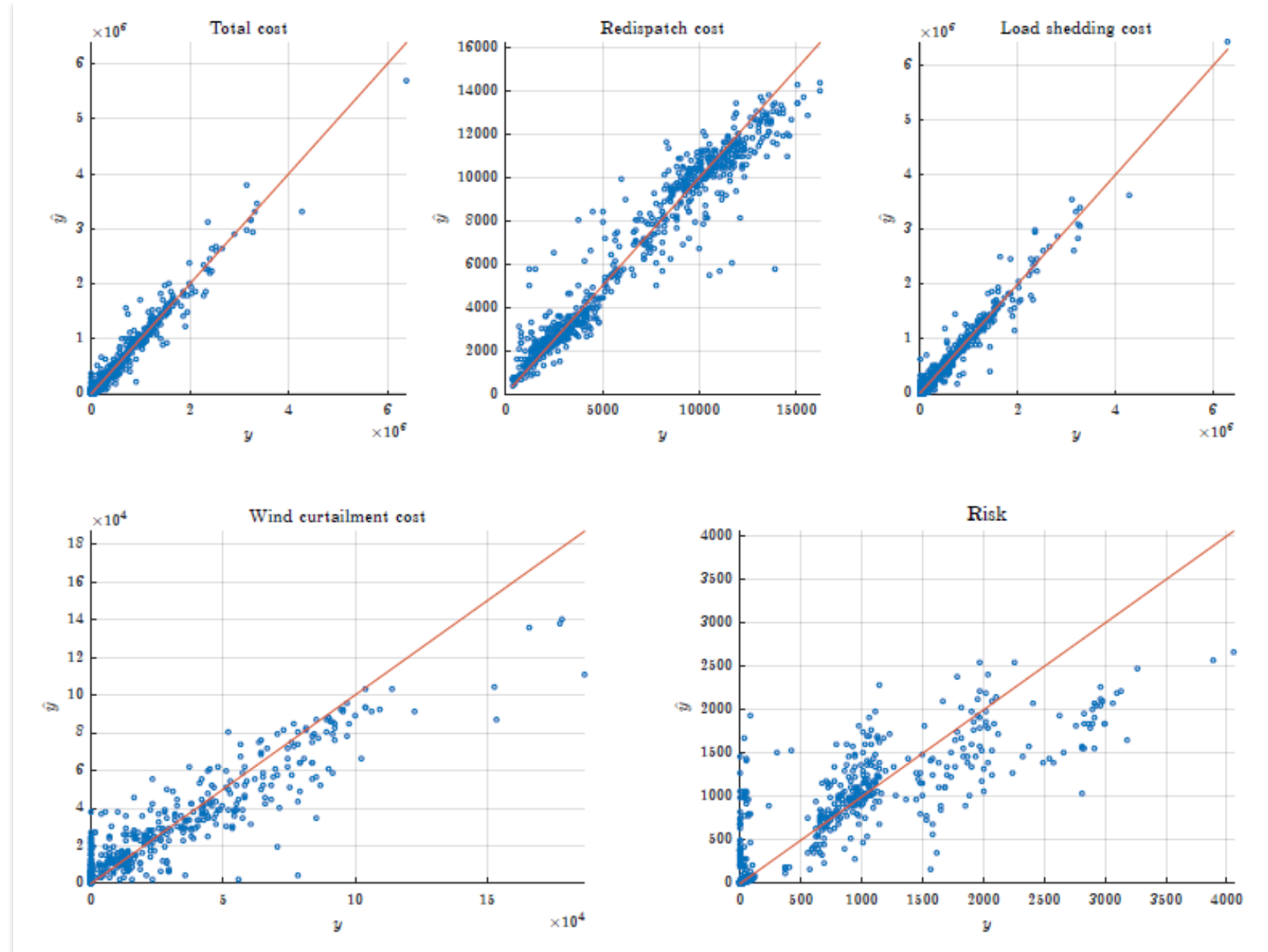
# Machine Learning of Proxies for the St-RMAC

- Tests on the **suitability of several learning algorithms** in order to predict :
  - real-time reliability control **costs**;
  - **risk** implied by real-time decisions;
- and, gain understanding of the real-time problem via **feature importance**.
- Database built while modeling the N-1 criterion for real-time operation.

# Machine Learning of Proxies



- Exemplary result:





# Conclusions





# The GARPUR RMAC






- Why?

- **adaptability** to the spatio-temporal variability to **threat probabilities & consequences**;
- **exploiting the full potential** of the system (e.g., corrective control) in a rational manner.

# Looking forward ...

- **Reliability management** was/is/will be a multi-stage & multi-level decision making under uncertainty problem;
  - **RMAC vision reachable** at the proof-of-concept level;
- 
- We could certainly make the most of recent advances:
    - in **simulation tools**, to more accurately study the dynamic behavior of the system & identify most prominent risks;
    - in **optimization & constraint satisfaction** to tackle the large-scale, non-convex, mixed-integer non-linear problems;
    - in **machine learning & statistics** to generate “proxies” for the large-scale assessment & optimization problems.

# To find out more...



Project no.:  
**608540**

Project acronym:  
**GARPUR**

Project full title:  
**Generally Accepted Reliability Principle with  
Uncertainty modelling and through probabilistic Risk assessment**

Collaborative project  
**FP7-ENERGY-2013-1**

Start date of project: 2013-09-01  
Duration: 4 years

**D2.2**  
**Guidelines for implementing the new reliability assessment  
and optimization methodology**

Due delivery date: 2016-08-31  
**Actual delivery date: yyyy-mm-dd**

Organisation name of lead beneficiary for this deliverable:  
**University of Liège**

- Please visit [www.garpur-project.eu](http://www.garpur-project.eu)
- **GARPUR D2.2** “Guidelines for implementing the new reliability assessment & optimization methodology”,
- **8 publications** in peer-reviewed conference proceedings.





**THANK YOU FOR YOUR ATTENTION!**

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