

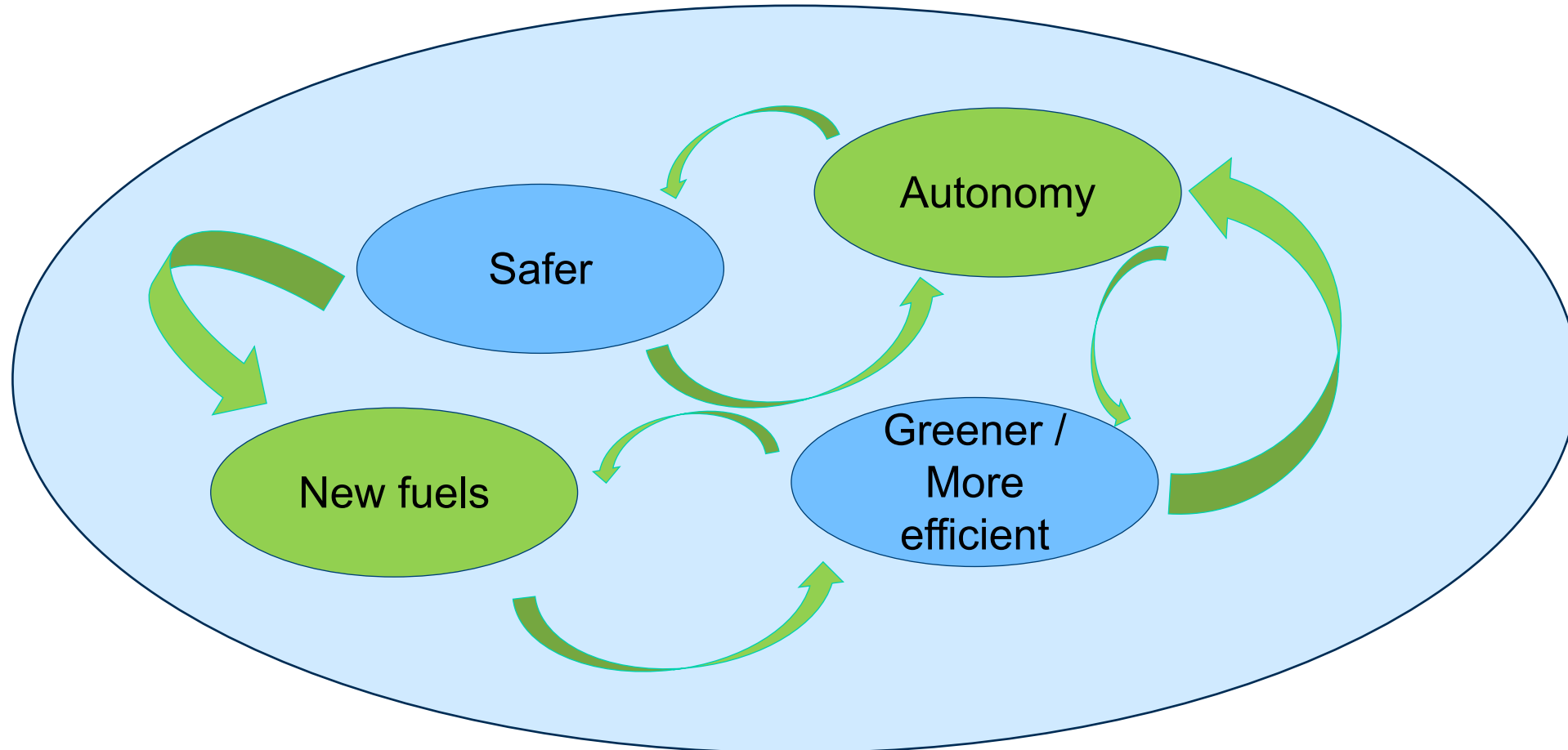
Utviklingen innen autonome og ubemannede skip og rollen til kontrollrommet med tanke på sikkerheten

HFC

Nils Haktor Bua, Section for new maritime technology







Section for new maritime technology



Norwegian waters VS international waters

Ship Safety
and Security
Act



MSC.1-
Circ.1455





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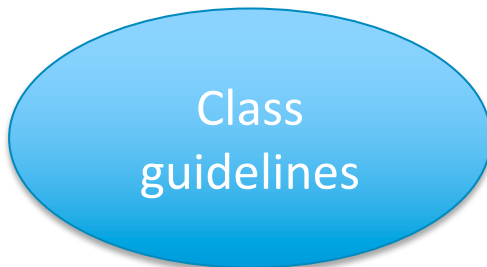
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MSC.1/Circ.1455
24 June 2013

**GUIDELINES FOR THE APPROVAL OF ALTERNATIVES AND EQUIVALENTS
AS PROVIDED FOR IN VARIOUS IMO INSTRUMENTS**

1 The Maritime Safety Committee, at its ninety-second session (12 to 21 June 2013), with a view to providing a consistent process for the coordination, review and approval of alternatives and equivalents with regard to ship and system design as allowed by the 1974 SOLAS Convention, as amended, and other mandatory IMO instruments, approved the annexed *Guidelines for the approval of alternatives and equivalents as provided for in various IMO instruments*.

2 Administrations and non-governmental organizations are invited to bring the annexed Guidelines to the attention of shipowners, shipbuilders, designers and system manufacturers.



Class
guidelines



E

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CIRCULARS

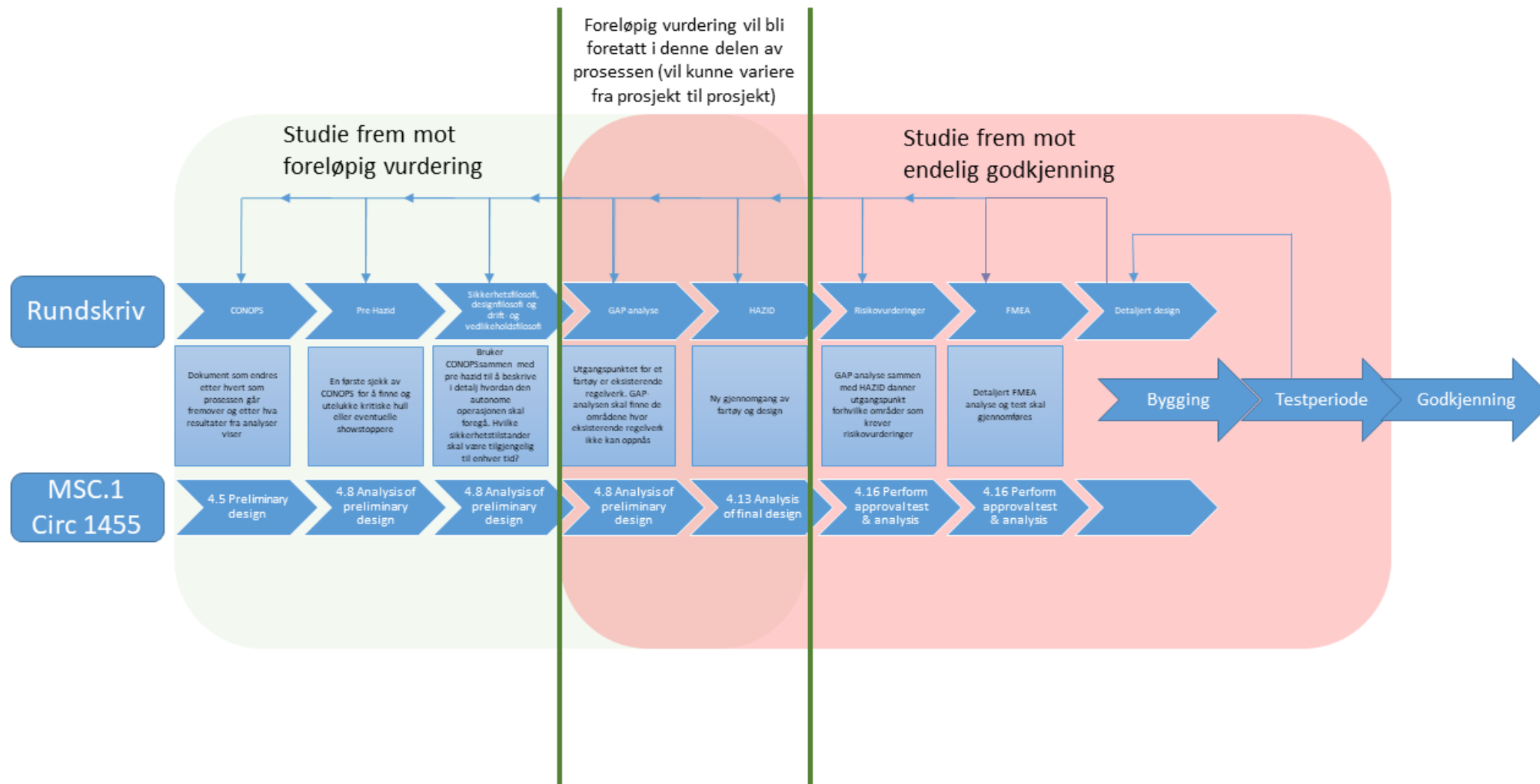
DATE: 8/27/2020 VALID TO: 12/31/2025 SERIES: RSV NUMBER: RSV 12 - 2020 CASE NUMBER: 2020/37328-1 SDM/JKS
CANCELS: FØRINGER I FORBINDELSE MED BYGGING ELLER INSTALLERING AV AUTOMATISERT FUNKSJONALITET, MED HENSIKT Å KUNNE UTFØRE UBEMANNET ELLER DELVIS UBEMANNET DRIFT

Guidance in connection with the construction or installation of automated functionality aimed at performing unmanned or partially unmanned operations

This Circular describes the documentation requirements and principles applied in the administrative processing of ships that are to be autonomous, and fully or partially remotely operated.

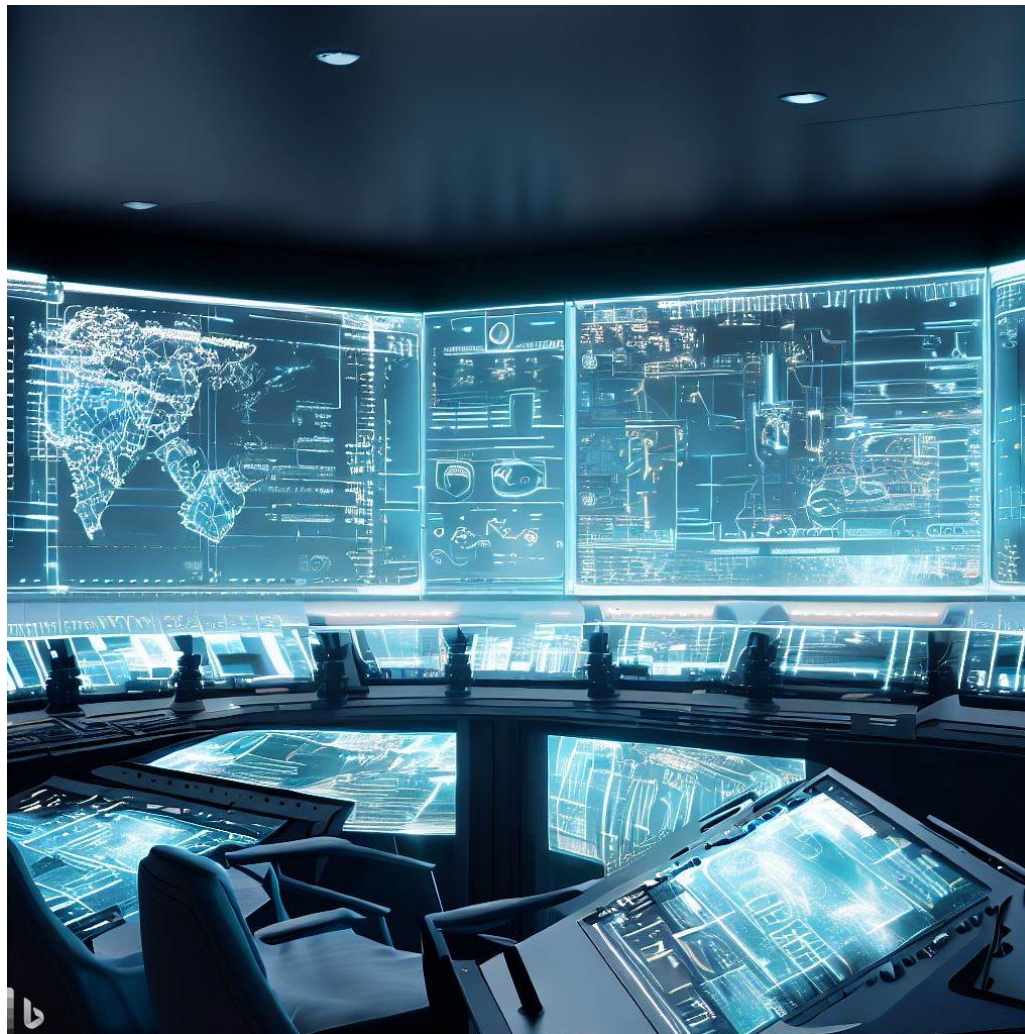
		MSC.1/Circ. 1455/2020	RSV
		4.5	
	1.1 Concept of operation - CONOPS	4.5	7.1
	1.2 Pre-HAZID		7.2
1. Preliminary Design	1.3 Safety philosophy		7.3
	1.4 Design philosophy		7.4
	1.5 Operation and maintenance philosophy		7.5
		4.8	
	2.1 Updated Pre-HAZID with associated		7.2
2. Analysis of preliminary design	2.2 Risk analyses/assessments		7.2
	2.2 Gap analysis		7.6
	2.3 HAZID and risk assessments		7.9
3. Analysis of final design		4.1	
	3.1 HAZID and risk assessments		7.9
		4.1	
4. Performance approval tests & analyses	4.1 Failure Mode and Effect Analysis (FMEA)		7.10
	Test requirements		9

Flytskjema prosess for autonomiprojekter (detaljert)





Remote control/operation center



Functions and responsibility shared between ROC and ship



Remote control/operation center - challenges



Today – 1 ship = one bridgeteam vs. future – one control room team handles several ships? How many?



How reliable and autonomous is the technology - to what extent must the control room monitor or intervene?



One dedicated control room always handles a ship or may the ship "jump" between control rooms?



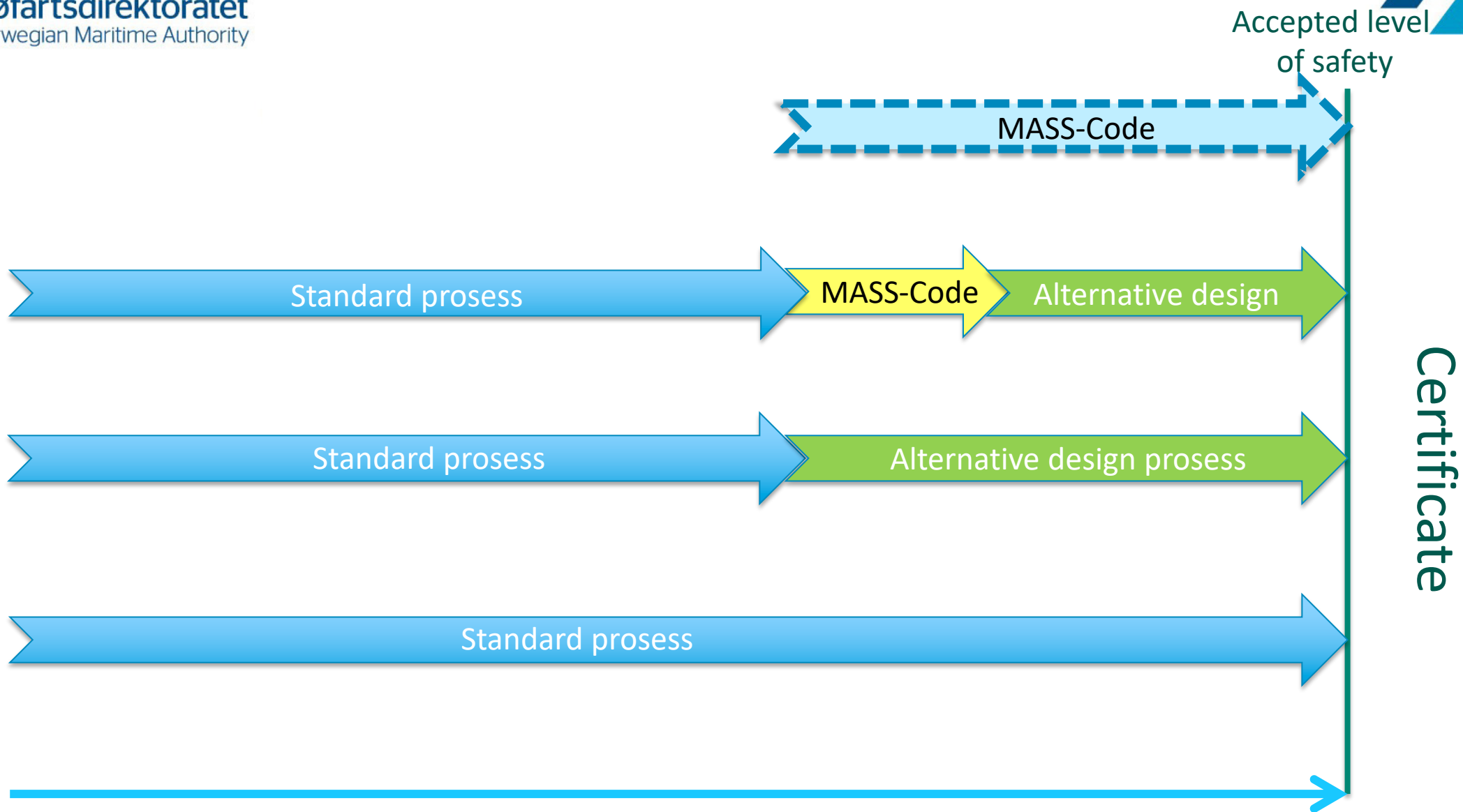
When international - to what extent are we willing to accept unmanned ships in Norwegian waters controlled from abroad?

MASS CODE – some output of the work so far

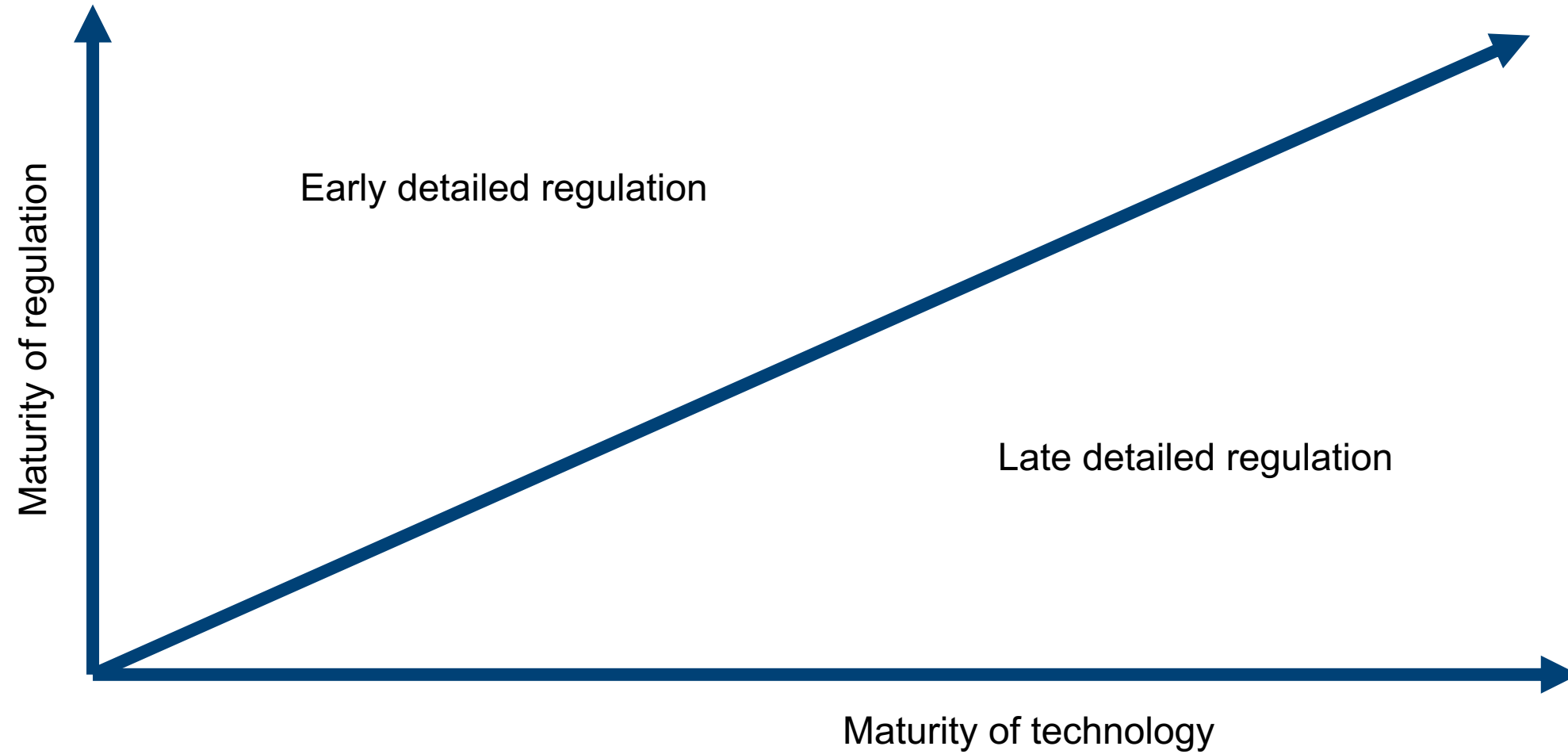


Joint MSC-LEG-FAL MASS Working Group:

- the Group agreed that:
 - .1 there should be a human master responsible for a MASS, regardless of mode of operation or degree or level of autonomy;
 - .2 such master may not need to be on board, depending on the technology used on the MASS and human presence on board, if any; and
 - .3 regardless of mode of operation or degree or level of autonomy, the master of a MASS should have the means to intervene when necessary.
- the Group agreed to the following definition for a remote operator (see also annex 1):
 - “Remote operator means a qualified person who is employed or engaged to operate some or all aspects of the functions of a MASS from a remote operations centre.”



When to regulate?



Testing

- Regulation 1042 regarding Marine equipment §§ 11 and 12
- The Norwegian test areas for autonomous shipping

Thank you!

Nils Haktor Bua

Check out:

[New maritim technology - sdir.no](https://sdir.no)

